

Resistivity method - Key points of this lecture

- ▶ Principles of resistivity measurements
 - ▶ Apparent resistivity
 - ▶ Geometry factor
- ▶ Measurement of resistivity in rock samples
- ▶ Resistivity measurements in the field
 - ▶ Instrumentation
 - ▶ Sounding and profiling
 - ▶ Configurations of electrode arrays
 - ▶ Applied potential
 - ▶ Pseudo-depth sections
- ▶ Interpretation
 - ▶ Depth and lateral contrasts
 - ▶ Examples
- ▶ Labs # 4 and 5
- ▶ Reading:
 - ▶ Reynolds, Section 7.4 – 7.5, 7.7
 - ▶ Dentith and Mudge, Sections 5.4 – 5.6

Principle of resistivity measurement

- ▶ According to the name of the method, in “resistivity” measurements, we determine **the resistivity ρ or conductivity $\sigma = 1/\rho$ of rock or subsurface layers**
- ▶ Generally, resistivity within rocks is always measured by (see your labs):
 - ▶ Injecting current I into a pair of electrodes connected to the rock sample or some locations on the ground, often denoted A and B (sometimes C_1 and C_2 , which mean “current”)
 - ▶ Measuring voltages (V , difference of electric potentials) between some other points. These points are conventionally denoted M and N (sometimes P_1 and P_2 , meaning “potential”)
 - ▶ Evaluating the **resistance** ratio $R = V/I$ of the whole circuit
 - ▶ Transforming R into **apparent resistivity ρ_a (explained on the next slide)** by formula:

$$\rho_a = Rk$$

where k is the “geometry factor” depending on the mutual positions of the electrodes

- ▶ Note that since the units for R are Ohm (Ω) and for ρ_a , the units are $\Omega \cdot \text{m}$, then the geometry factor k **has units of distance**
 - ▶ k has the meaning of “ A/L ”, where A is the “characteristic area” crossed by the current, and L is the “characteristic length” of the array
- ▶ In modern studies with large numbers of data points, the apparent resistivity step is often bypassed and replaced by **direct inversion for the subsurface model** (ERT, “electrical resistivity tomography”)

Apparent resistivity

- ▶ The **apparent resistivity** is the key concept used when transforming, presenting, or interpreting resistivity data
 - ▶ Usually, “apparent resistivity” ρ_a means **the resistivity of a spatially uniform body** (rock sample, layer, or the whole subsurface) **that would explain the measured resistance R**
 - ▶ For uniform bodies, ρ_a equals the true resistivity (ρ)
 - ▶ For non-uniform bodies, this quantity differs from the true resistivity
 - ▶ Apparent resistivity depends on the type and size of the electrode array used and location of measurement

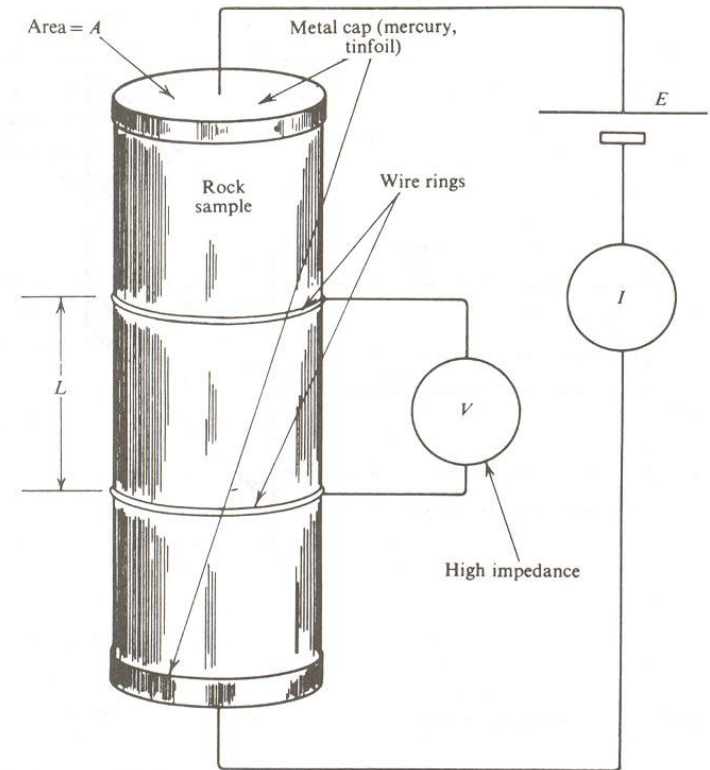
Resistivity of rock samples

- ▶ In rock cores, measurement of resistivity is relatively straightforward as shown in this figure

- ▶ Current electrodes are attached to the ends of the core. In a good approximation, the rock is uniform, and the current density is j constant throughout the volume:
 - ▶ $j = I/A$ (A is the cross-sectional area)
- ▶ Potential electrodes are made of two wire rings (see figure)
 - ▶ The voltage measurement circuit has high resistance (impedance), and it does not distort the current
 - ▶ Electric field between the rings: $E = V/L$
- ▶ Thus, considering only the portion of the core between the wire rings, the **apparent resistivity equals the true one**, and the “**geometry factor**” $k = A/L$:

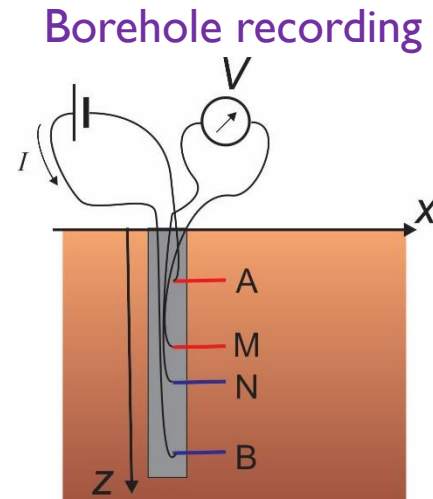
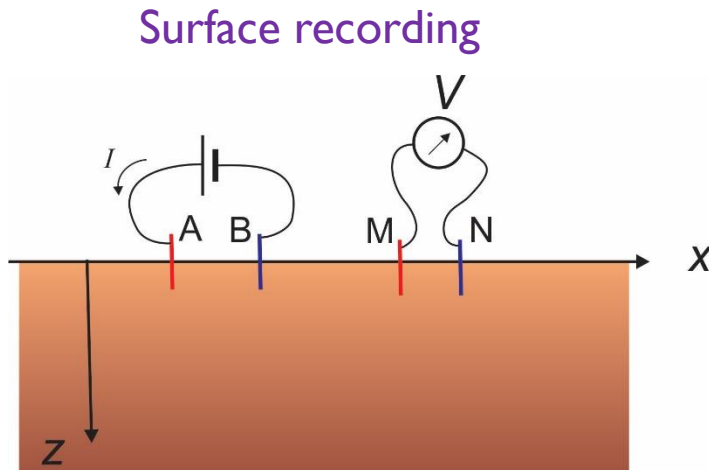
$$\rho_a = \rho = \frac{E}{j} = \frac{V}{I} \frac{A}{L}$$

Geometry Factor, k



Resistivity measurements in the field

- ▶ In the field, the goal of resistivity measurements is to create 1-D ($\rho(z)$), 2-D ($\rho(x,z)$), or 3-D ($\rho(x,y,z)$), or similar conductivity $\sigma = 1/\rho$ images of subsurface layers
 - ▶ This is done by using surface or borehole arrays as shown in cartoons below
 - ▶ Moving the arrays laterally to cover extended areas is usually called “**profiling**”. Expanding the arrays while remaining at the same place (to vary the depth of coverage) is called “**sounding**”.



Field procedures

- ▶ There are two general styles of acquisition
 - ▶ Field procedures are optimized for safety and minimal movement of long wires and cables:
- 1. Vertical (depth) sounding
 - ▶ Uses a **fixed center** with expanding spread
 - ▶ Measures the vertical variation of resistivity for a given geologic section
 - ▶ Frequently done at several locations, even if lateral profiling is the primary objective
 - ▶ To establish proper electrode spacing for profiling
 - ▶ To improve depth control
 - ▶ As shown in the following slides, **arrays with electrodes at infinity** (“pole arrays”) or “gradient arrays” are usually used for profiling, because these arrays require fewer wires to be moved
- 2. Lateral profiling (horizontal or downward in a borehole)
 - ▶ Current and potential electrodes are shifted over the survey area without altering their relative configuration
 - ▶ Focuses on lateral variation of resistivity down to some depth.
 - ▶ Best suited for detection of lateral contacts (e.g., steeply dipping dikes, or layers when in borehole).

Instrumentation and field gear

- ▶ Common resistivity gear looks like this: source/battery, receiver, electrodes, and four wires to locations A, B, M, and N
- ▶ For low-voltage measurements (IP, SP, large distances), **nonpolarizing electrodes** are required



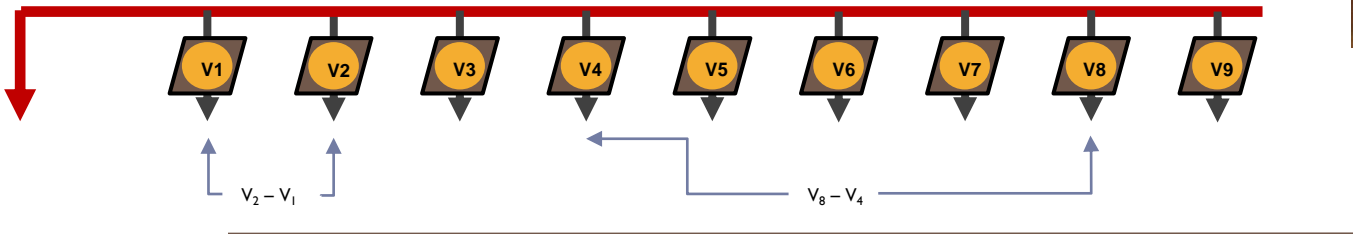
SYSCAL resistivity meter
used in our field schools
and labs

Large 3-D array recording

- ▶ Recent trend in receiver technology uses **hundreds of small, independent receivers** recording voltages and transmitting data wirelessly
- ▶ Only **one, common reference wire** is needed
- ▶ This array provides **hundreds of pole-pole recordings of the same source** simultaneously
 - ▶ “M-N” pairs of these recordings can be used to form multiple arrays
 - ▶ Data are inverted by Electric Resistivity Tomography (ERT, see section 7.6 in Reynolds text)



Common reference wire grounded at infinity



Geometry factor for an arbitrary surface array

- ▶ As explained in the [intro to electrical methods lecture](#), for a homogeneous half-space with resistivity ρ , the potentials produced at points M and N represent sums of contributions from point source at A and a sink (negative source) at B (“basic solution #2” there):

$$V = \varphi_M - \varphi_N = \frac{I\rho}{2\pi r_{AM}} - \frac{I\rho}{2\pi r_{BM}} - \left(\frac{I\rho}{2\pi r_{AN}} - \frac{I\rho}{2\pi r_{BN}} \right) = \frac{I\rho}{k}$$

where $r_{...}$ denote the distances between the corresponding electrodes, and k is the geometry factor for the arbitrary array (the array can even be in 3D):

$$k = 2\pi \left(\frac{1}{r_{AM}} - \frac{1}{r_{BM}} - \frac{1}{r_{AN}} + \frac{1}{r_{BN}} \right)^{-1}$$

Note that this formula illustrates **the reciprocity** - sources AB can be interchanged with NM

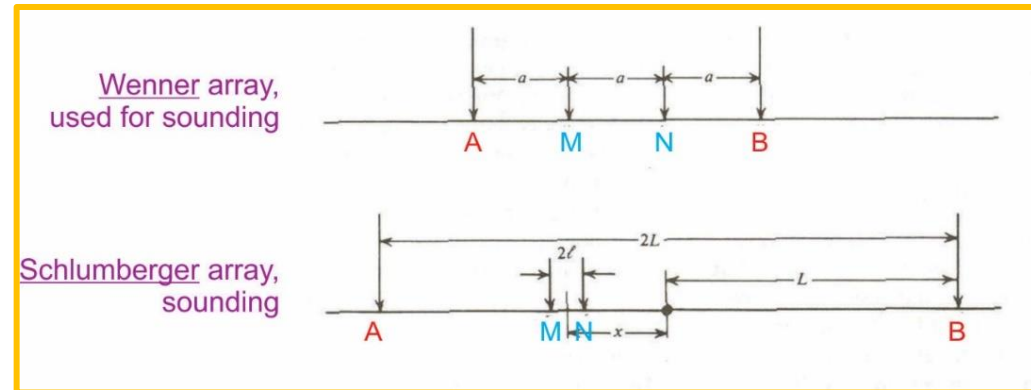
- ▶ From the first equation above, the apparent resistivity estimated from resistance $R = V/I$ equals the true one for the uniform half-space:

$$\rho = \frac{V}{I} k$$

Common array configurations

- ▶ Different configurations of electrode arrays are used for different targets and goals of experiment (profiling or sounding):

- ▶ Wenner array: four electrodes are spaced by a common distance a
 - ▶ Single parameter is convenient for calculation, plotting sections, and interpretation
 - ▶ However, profiling with this array is difficult, because it requires moving all electrodes and wires every time the array is moved
 - ▶ Geometry factor: $k = 2\pi a$



- ▶ Schlumberger array: most common for sounding

- ▶ With fixed A and B, several M and N are tried, and then A, B is changed
- ▶ Usually spacing between current electrodes $L \gg l$ (spacing between potential electrodes)

- ▶ Geometry factor: $k \approx \frac{\pi}{2l} \frac{(L^2 - x^2)^2}{L^2 + x^2} = \frac{\pi L^2}{2l}$ (when $x = 0$)

Common array configurations

▶ Pole-dipole array

- ▶ One of current electrodes is at infinity (does not have to be moved), and so profiling is easier

$$k = 2\pi \frac{ab}{b-a}$$

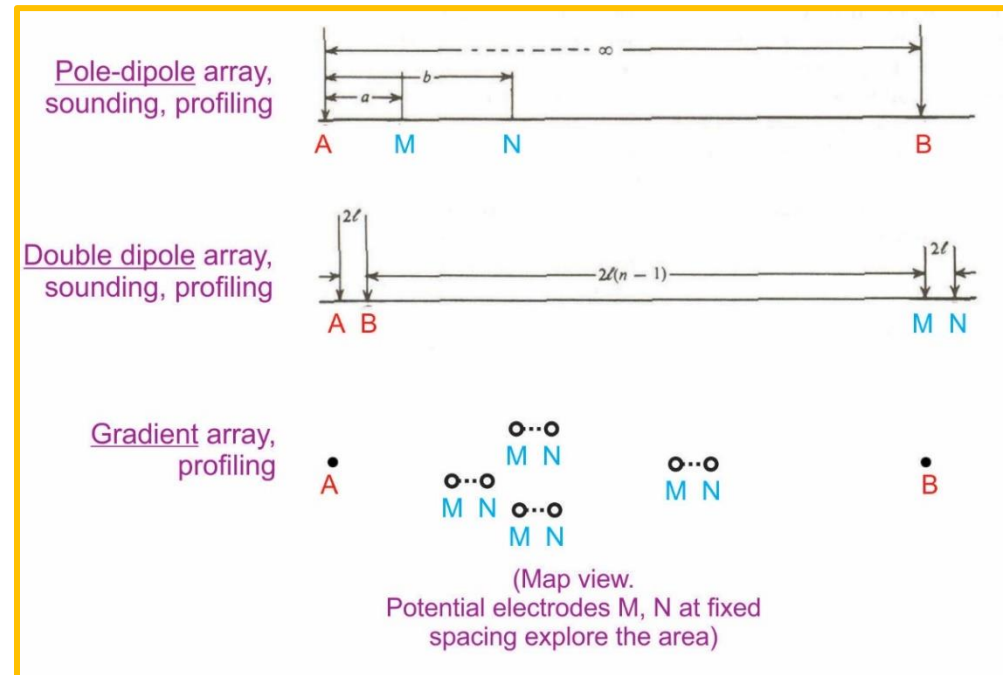
▶ Double-dipole array

- ▶ Current electrodes are fixed at close spacing, and potential electrodes are moved, also keeping close spacing
- ▶ Dipole-dipole configurations are sensitive to gradients of the field and deeper structures

$$k = 2\pi l(n-1)n(n+1)$$

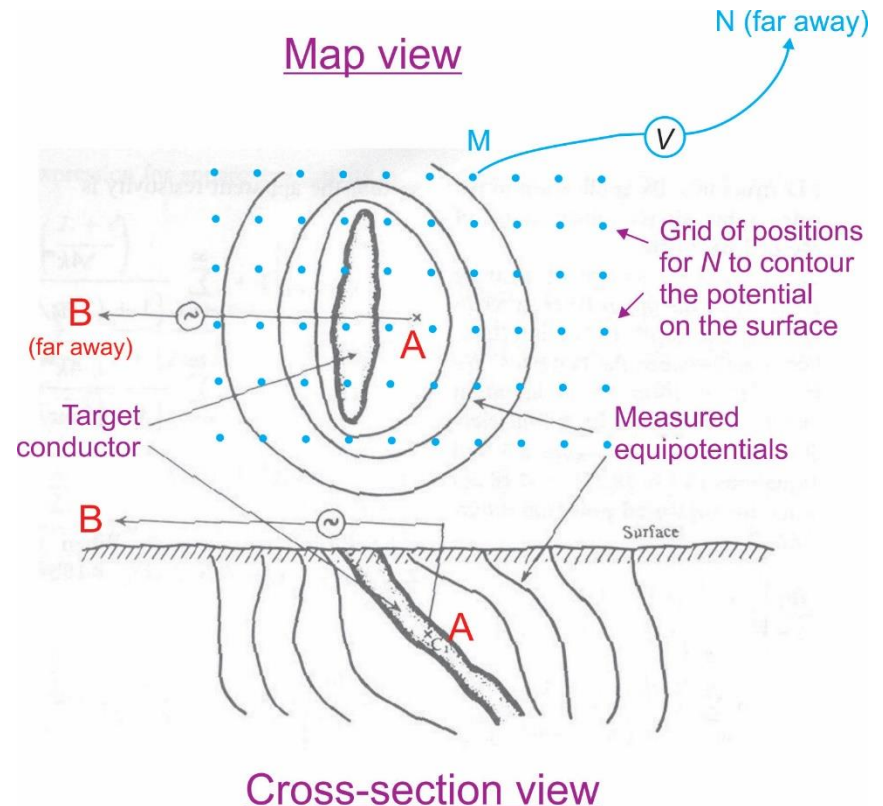
▶ Gradient array

- ▶ Current electrodes are widely spaced, potential electrodes explore the area between them
- ▶ Also sensitive to field gradients



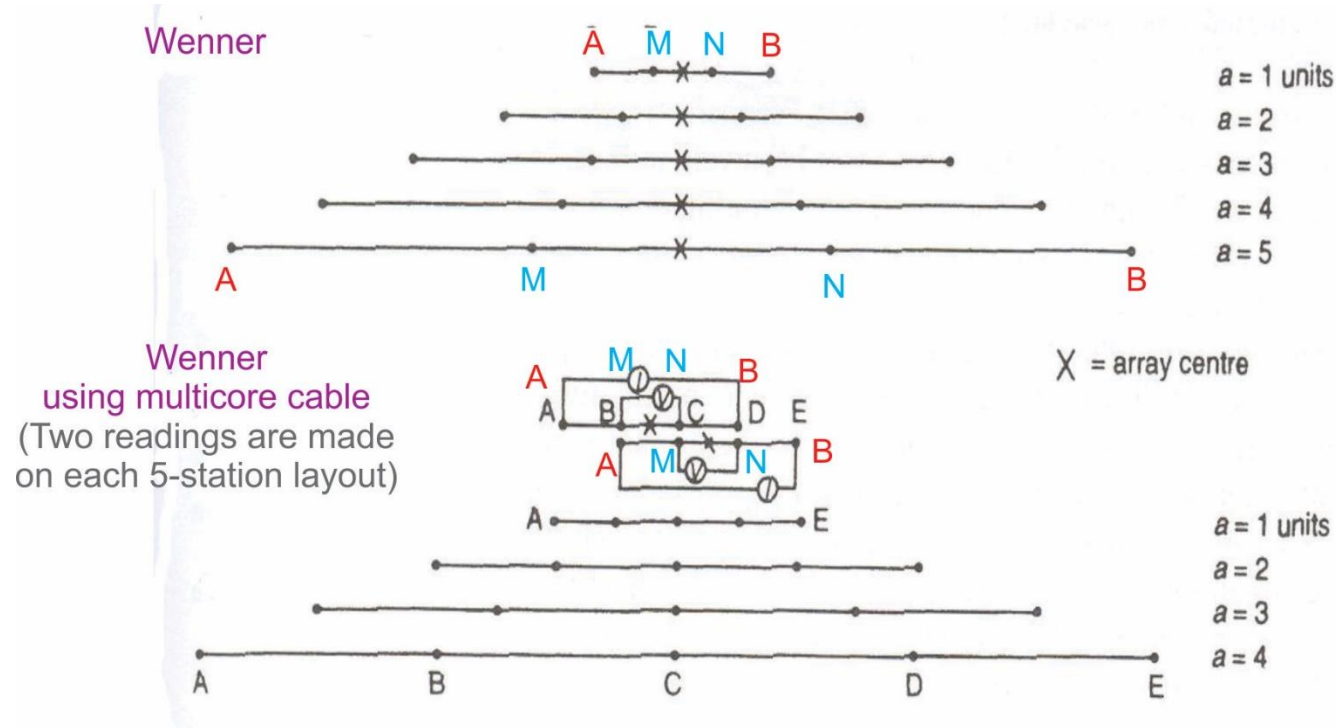
Applied potential (Mise-à-la-masse)

- ▶ The **Applied potential** method uses a pole-dipole array in which the **current electrode is embedded into the conductive zone**
 - ▶ In seismology, there is a similar idea of “salt proximity” surveys (see GEOL335)
- ▶ Does not require moving the current electrodes; **only one potential electrode M is moved**
- ▶ Allows mapping the extent, dip, strike, and continuity of the conductive zone better than by usual mapping
 - ▶ By using “depth continuation” (numerical solution of the Poisson’s equation for the potential), surface map of potential $\phi(x,y)$ can be transformed into depth image $\phi(x,y,z)$ (bottom of this figure)



Expanding arrays for depth sounding

- ▶ **Depth sounding** is performed by repeated recording with increasing spacing of the array
- ▶ If multicore cable is available, several lateral array positions and spacings a can be recorded in one deployment

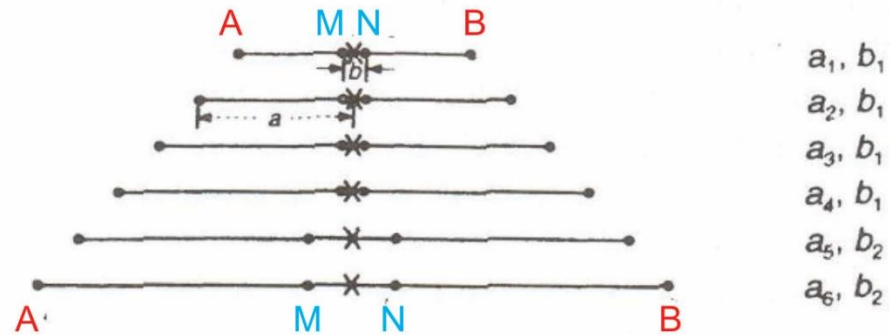


Expanding arrays for depth sounding

- ▶ Patterns of expanding spreads for Schlumberger and dipole-dipole arrays
- ▶ Again, **the idea is to try a range of distances between AB and MN** while minimizing moves of long wires

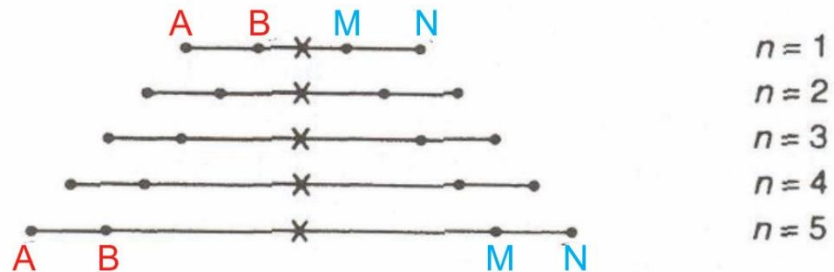
Schlumberger:

- 1) Make several increments in AB keeping MN fixed
- 2) Increase MN and make increments in AB, etc.



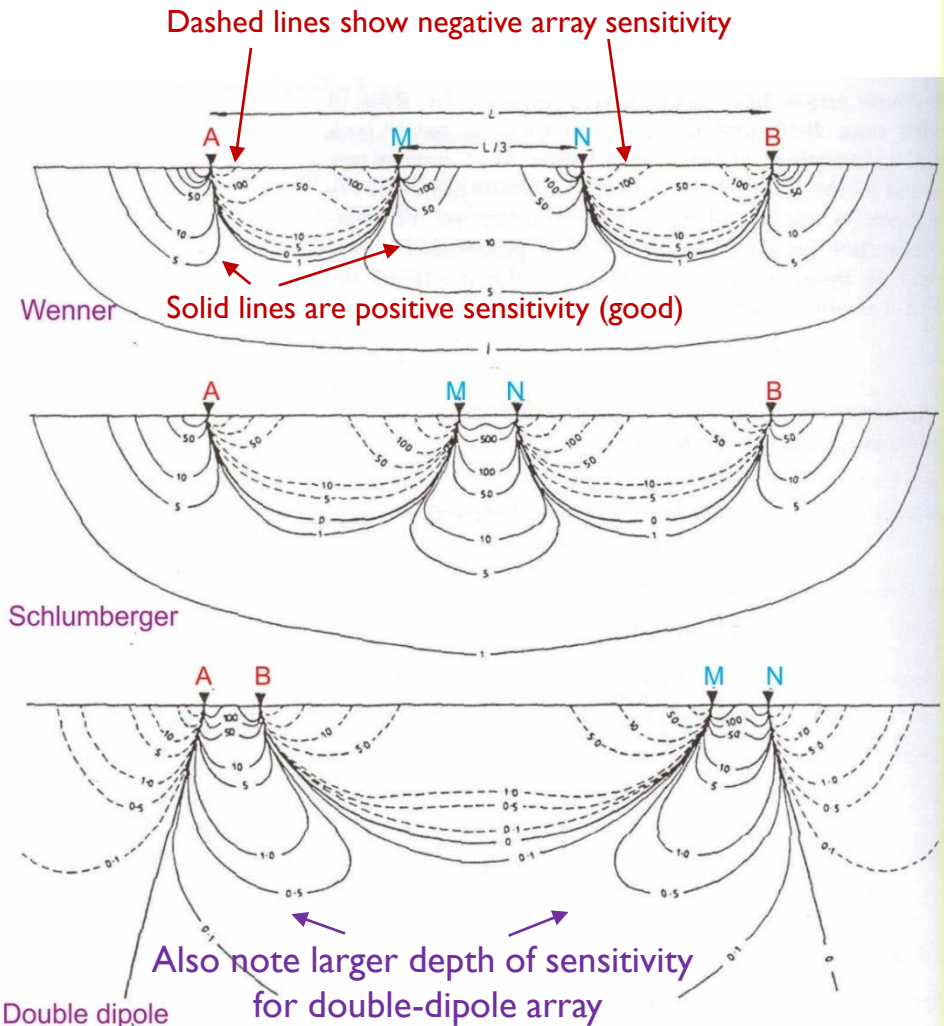
Dipole-dipole:

Expand keeping the current and potential electrodes close together (this is easier than moving very long wires)



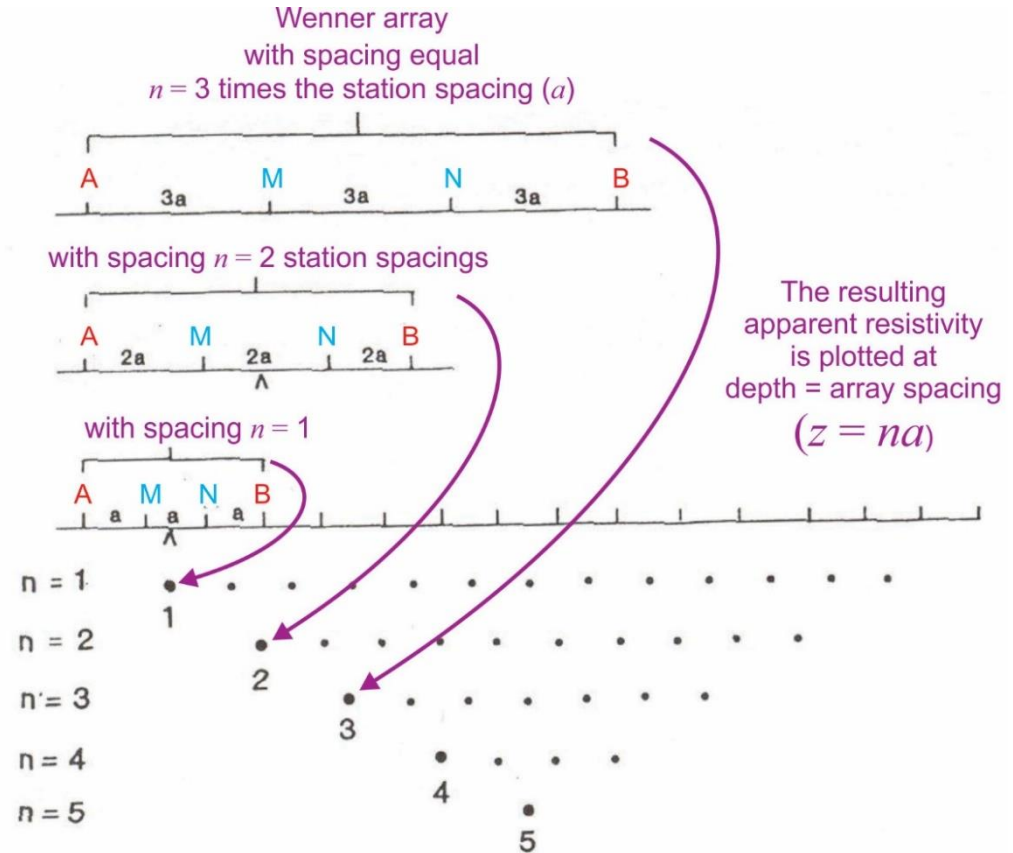
Array sensitivity

- ▶ If we insert a resistive body in the ground, will this increase the apparent resistivity measured by an array?
 - ▶ The answer to this question is not obvious and not simple
- ▶ The answer is given by **Array sensitivity** model, which is the change of the apparent resistivity (ρ_a) produced by a unit-volume resistive sphere added at point (x,z) in the ground
 - ▶ With positive sensitivity, a resistive (or conductive) anomaly in the ground would accordingly increase (decrease) the apparent resistivity. This is how you would intuitively interpret resistivity measurements
- ▶ However, note that at shallower depths between the pair of MN and current electrodes, the **sensitivity is negative** – a resistive/conductive body there would look like an decrease/increase of the apparent resistivity



Pseudo-section (pseudo-depth section)

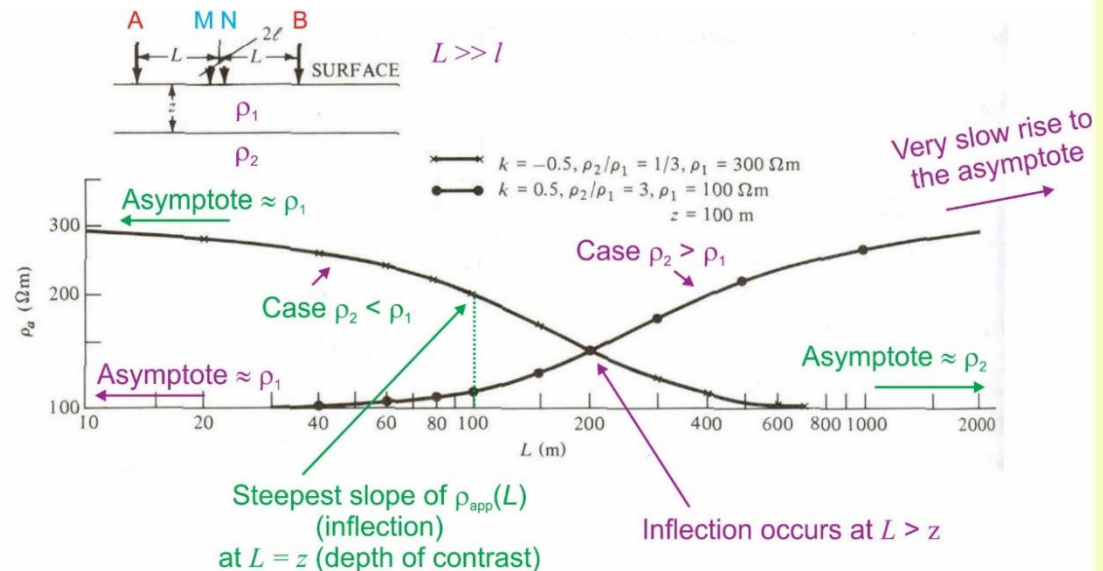
- ▶ For profiling with an expanding array (or multicore sounding), the results can be conveniently presented in the form of a “pseudo-depth section”
- ▶ For each configuration of the array, the resulting ρ_a is plotted at lateral “pseudo-position” and “pseudo-depth”
 - ▶ These coordinates roughly represent the point of maximum sensitivity of ρ_a to true resistivity
 - ▶ These coordinates are not accurate, but rather defined by convention
 - ▶ They often give a reasonable idea about the distribution of resistivity with depth and laterally
 - ▶ Useful for comparing different datasets



Interpretation of depth variations of resistivity – basic idea

- ▶ For a resistive layer overlaying a more conductive ground ($\rho_2 < \rho_1$ and green in the figure below), the resistivities can be seen from the asymptotes of ρ_{app} in depth sounding (e.g., by Wenner or Schlumberger arrays)
 - ▶ For $L \ll z$, the current flows mostly through the upper layer, and $\rho_a \approx \rho_1$
 - ▶ For, $L \gg z$, the current flows mostly through the lower layer, and $\rho_a \approx \rho_2$
 - ▶ The inflection in the $\rho_{app}(L)$ curve occurs near $L = z$ (depth of the contrast)

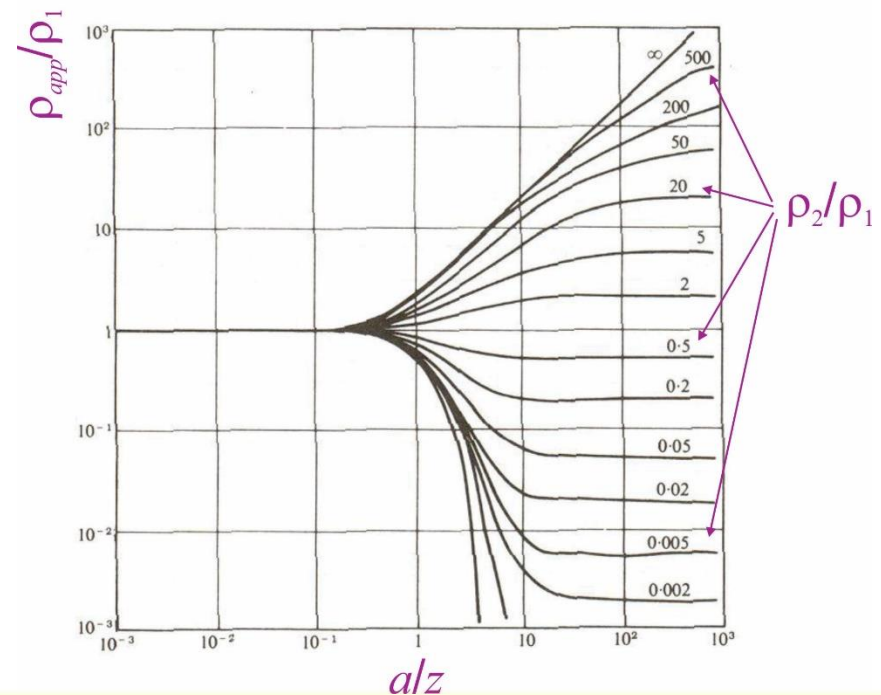
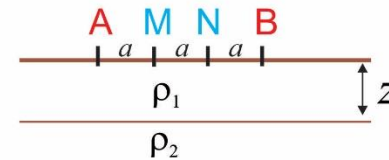
- ▶ For $\rho_2 > \rho_1$ (resistive deep part of the model), the situation is not so easy (purple):
 - ▶ The asymptote at $L \ll z$ is still correct because the current flows through the upper layer
 - ▶ However, the asymptote at $L \gg z$ is practically not achieved
 - ▶ This is because the current is concentrated within low-resistivity layers and tends to avoid resistive ones



Interpretation – two-layer models

- ▶ Quantitative fitting of two-layer resistivity models can be done by plotting the observed and $\rho_a(\text{array_spacing})$ dependencies in scaled (unitless) axes and matching them against modeled master curves
 - ▶ For Wenner array, only one set of master curves is needed for variable resistivity contrast between layers

Master curves for Wenner array over two layers



Interpretation – “complete curve matching” method

- ▶ That was for Wenner array, and [here is how you can find \$\rho_1\$, \$\rho_2\$, and \$z\$ for any array](#):
- ▶ From the “basic case #4” in the [preceding lecture](#), recall that for a two-layer resistivity, the potential φ at distance r from a current source or sink can be modeled as

$$\varphi(r) = \frac{I\rho_1}{2\pi} \left(\frac{1}{r} + \sum_{i=1}^{\infty} \frac{2k^i}{r_i} \right)$$

were k is the “reflection coefficient” for resistivity: $k = \frac{\rho_2 - \rho_1}{\rho_2 + \rho_1} = \frac{\rho_2/\rho_1 - 1}{\rho_2/\rho_1 + 1}$

Unfortunately, this is also denoted “ k ”, but this is not geometry factor

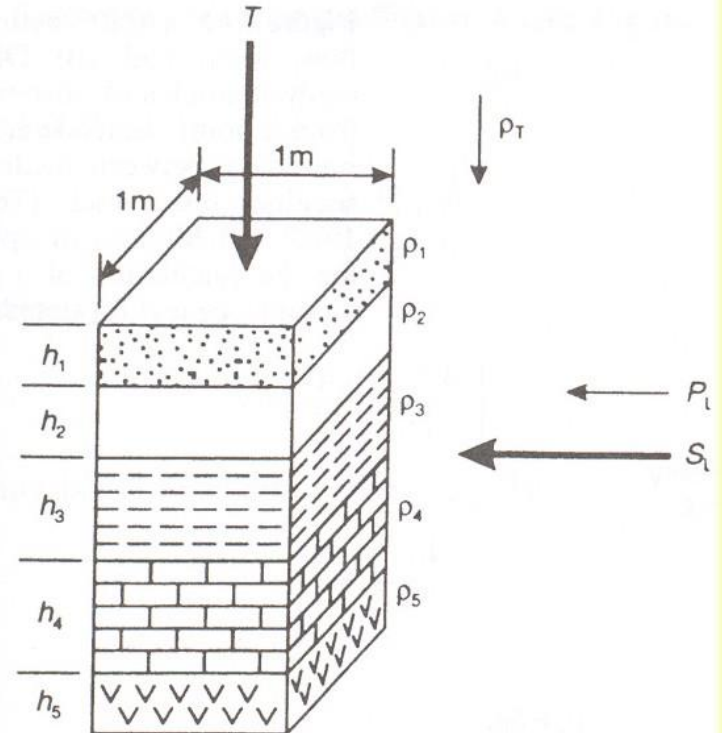
- ▶ From this $\varphi(r)$, the $\rho_a(L)$ can be expressed for any array by using geometry factors (see [this lecture](#))
- ▶ Therefore, **the complete $\rho_a(L)$ curve can be easily modeled for parameters z and k** . The **complete-curve matching method** is then:
 1. From the asymptote at $L \rightarrow 0$, estimate $\rho_1 = \rho_a(L \rightarrow 0)$
 2. Divide your data $\rho_a(L)$ by ρ_1 , model it for a range of z and k , and find the best-fit pair (z, k)
 3. From the value of k , determine ρ_2 (equation above): $\rho_2 = \rho_1 \frac{1+k}{1-k}$

Layer equivalence

- ▶ Similar to gravity, there exists a significant uncertainty in resistivity interpretation. This uncertainty should be realized to avoid pitfalls.
 - ▶ The problem is that resistivity is likely anisotropic, i.e. different in vertical and longitudinal (horizontal) directions

- ▶ Here is a list of **all (in principle) measurable parameters** for a stack of layers (“dar Zarrouk parameters”):
 - ▶ Longitudinal (horizontal) conductance $S = h/\rho_L = h\sigma_L$
 - ▶ Longitudinal resistivity $\rho_L = h/S$
 - ▶ Transverse resistance $T = h\rho_T$
 - ▶ Transverse resistivity $\rho_T = T/h$
 - ▶ Anisotropy $A = \rho_T/\rho_L$

- ▶ If considering anisotropy, **it is impossible to uniquely determine both resistivity and thickness of any layer!**

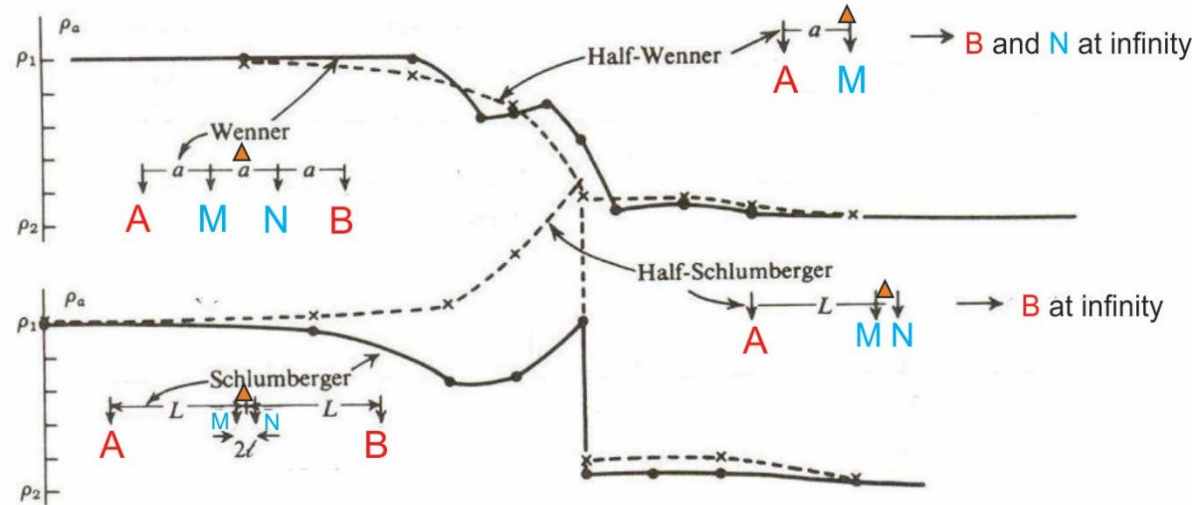


Profiling example: lateral resistivity contrast

- ▶ Note that due to the extent of array, $\rho_a(x)$ shows a complex patterns when the array passes a vertical contact
- ▶ Note the rising $\rho_a(x)$ when approaching the low-resistivity zone (ρ_2). This is because of the **negative array sensitivity** discussed above
- ▶ These lateral patterns should be removed by rigorous inversion

Apparent resistivity profiles over a vertical resistivity contrast for four arrays

▲ - "location of "station" in resistivity graphs for each array



Resistivity cross-section



Profiling example: resistive dike

- ▶ Example of a narrow dike of thickness b equal half of the spacing of the electrode array (a or L) shows the shape of ρ_a response in detail
 - ▶ **Symmetric/asymmetric** for symmetric/asymmetric arrays
 - ▶ Response is usually **much smaller than true resistivity but close for pole-dipole array**
 - ▶ The response is inverted for the pole-pole array (because of its **negative sensitivity** at this point)
 - ▶ When using the double dipole array, TWO images of the dike are obtained when either the current or potential electrodes pass the target (because of **reciprocity**)

