Reflection Seismic Data Processing

- General CMP processing sequence
- Highlights of some steps

Reading:

Sheriff and Geldart, Chapter 9

Reflection Seismic Processing

- Objective transform redundant reflection seismic records in the *time domain* into an interpretable *depth image*.
- Four general stages of data processing:
 - Data reduction and editing;
 - Transformation into conveniently computermanageable form;
 - Removal of bad records;
 - Gathering;
 - CMP sorting;
 - Filtering in time and space;
 - Attenuation of noise;
 - Imaging
 - Final velocity and reflectivity image.

Seismic Processing Systems

- Seismic processing requires extensive support by software
 - Highly integrated
 - High performance
 - Interactive and batch processing
- Usually geared to a particular type of application
 - Mostly CMP reflection processing;
 - Land or marine, 2D or 3D.
- Commercial:
 - ProMAX (Landmark);
 - Omega (Western Geophysical, marine);
 - Echos (formerly Disco, Focus Paradigm);
 - Vista (now Schlumberger/CGG)
- Universities:
 - Stanford Exploration Project;
 - Seismic UNIX (Colorado School of Mines);
 - FreeUSP (Amoco);
 - SIOSEIS (Scrippts, marine);
 - Our own (IGeoS)

CMP Processing Sequence (initial data reduction)

- 1) Demultiplex, Vibroseis correlation, Gain recovery
 - Conversion from file formats produced by field data loggers into processing-oriented formats
 - > SEG-Y, SEG-2.
 - ProMax, Focus, Omega, SU, Vista, etc., internal formats.
 - Often done in the field.
- 2) Field Geometry
 - Assignment of source-receiver coordinates, offsets, etc. in the *trace headers*.
- 3) Edit
 - Removal of bad traces (noisy channels, poorly planted geophones, channels contaminated by power line noise, etc.).

CMP Processing sequence (statics)

4) First arrival picking

- May be semi-automatic or manual;
- Required for generation of *refraction statics*; models and for designing the *mutes*.

5) Elevation statics

- Based on geometry information, compensates the traveltime variations caused by variations in source/receiver elevations.
- Transforms the records as if recorded at a common horizontal *datum* surface.

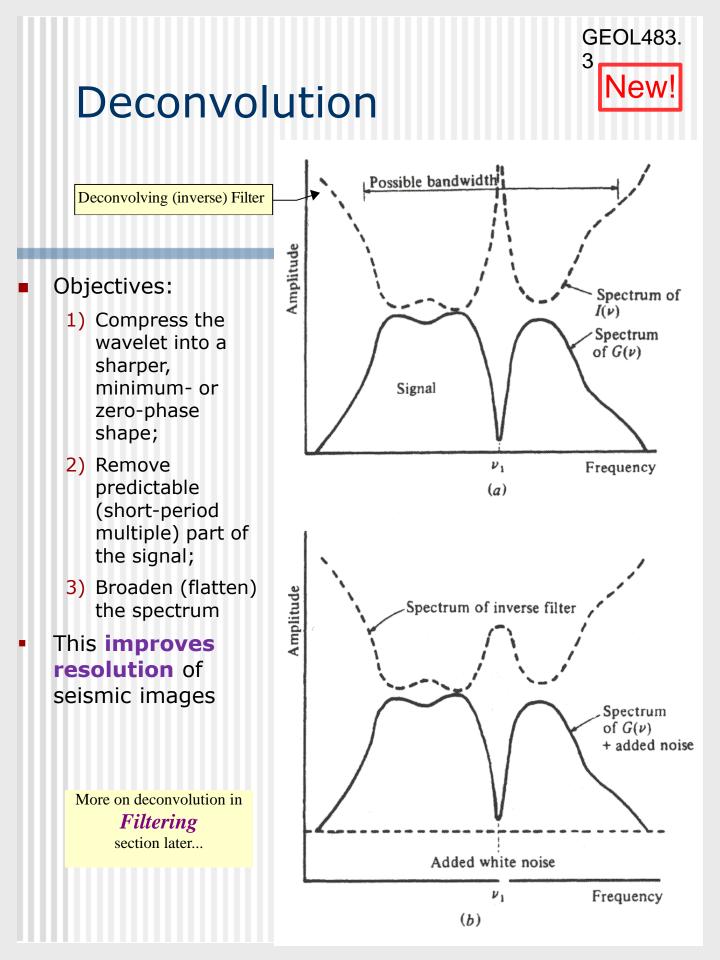
6) Refraction statics

- Builds a model for the shallow, low-velocity subsurface;
- Compensates travel-time variations caused by the shallow velocities.

CMP Processing Sequence (continued)

7) 'Top', 'bottom', and 'surgical' <i>mute</i>				
 Eliminates (sets amplitude=0) the time intervals where strong non-reflection energy is present: 				
 First arrivals, ground roll, airwave. 				
8) Amplitude recovery				
 Compensates geometrical spreading; 				
 Based on a simple heuristic relation. 				
9) Trace balance				
 Equalizes the variations in amplitudes caused by differences in <i>coupling</i>; 				
 In true-amplitude processing, replaced with `surface-consistent deconvolution'. 				
10) Deconvolution or wavelet processing				
 Compresses the wavelet in time, attenuates reverberations. 				
 Converts the wavelet to zero-phase for viewing 				
11) Gather, CMP sort				
 Often (in ProMax, Omega, Vista) done by using trace lookup tables instead of creating additional copies of the dataset. 				
12) Moveout (Radon, <i>τ-p, f-k</i>) filtering				
 Attenuates multiples, ground roll. 				

more steps will be continued later ...



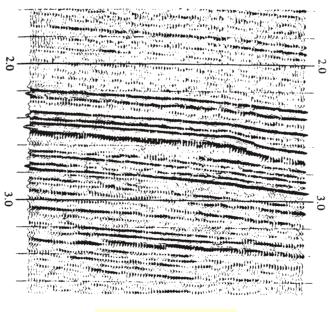


Time (s)

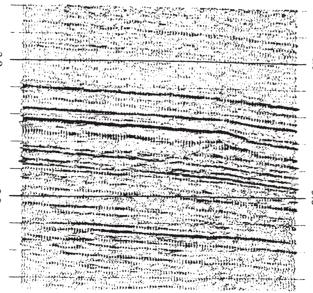
Wavelet shaping

- Shape of the source wavelet is estimated from autocorrelation of the data
- Time-variant "spectral whitening" (flattening within an estimated bandwidth) is applied
- A filter is designed to convert the wavelet into zerophase

Note the sharper resolution of layering after wavelet improvement



Migrated stack before wavelet processing



Migrated stack after wavelet processing

CMP Processing Sequence (continued)

13)	Velocity	ana	lysis
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- For each of the CMP gathers, determines the optimal *stacking velocity*.
- 14) Dip Moveout (DMO) correction
 - Transforms the records so that the subsequent NMO+stack work well even in the presence of dipping reflectors.
- 15) Normal Moveout (NMO) correction
 - Removes the effects of source-receiver separation from reflection records;
 - Transforms the records as if recorded at normal incidence.
- 16) Residual statics
 - Removes the remaining small travel-time variations caused by inaccurate statics or velocity model
- Steps 13-16 are usually <u>iterated</u> 3-5 times to produce accurate <u>velocity</u> and <u>residual statics</u> models.
 - This is because the success of velocity analysis depends on the quality of DMO/NMO and residual statics, and vice versa

more steps will be continued later, and now, let us consider velocity analysis, NMO and DMO ...

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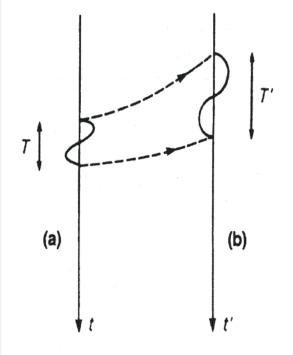
Normal Moveout (NMO) correction and stretching

NMO correction transforms a reflection record at offset x into a normal-incidence (x=0) record:

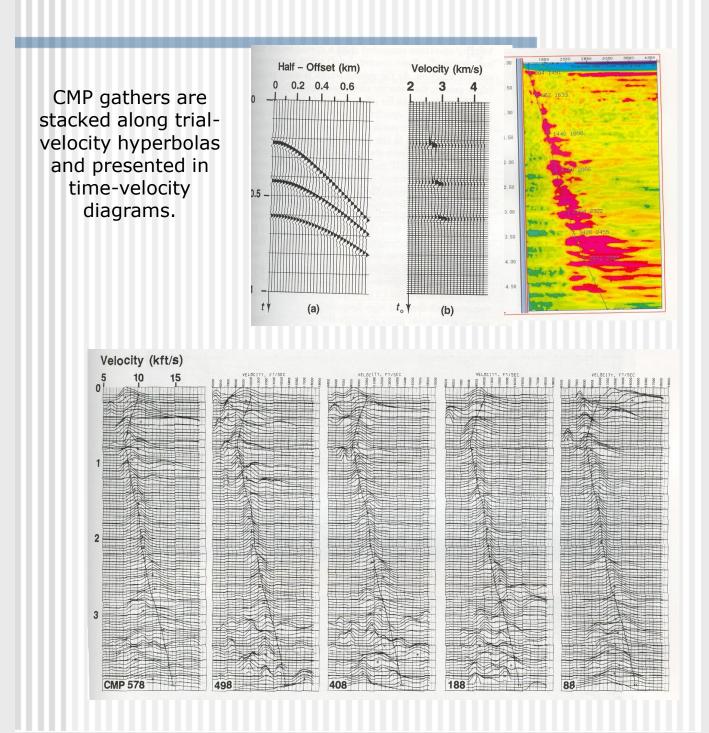
$$t_{0} = \sqrt{t^{2}(x) - \left(\frac{x}{V}\right)^{2}} \approx t(x) - \frac{1}{2t_{0}}\left(\frac{x}{V}\right)^{2}$$

"Stacking velocity"

- NMO correction stretches shallower and slower reflections stronger
 - This affects the spectrum of the stack
 - This distortion is controlled during processing by setting a limit in relative stretch (typically ~25%)

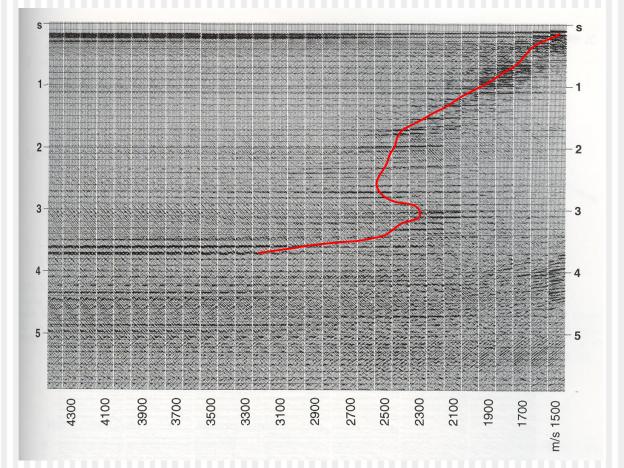


Velocity Analysis



Velocity analysis (Common-Velocity Stacks)

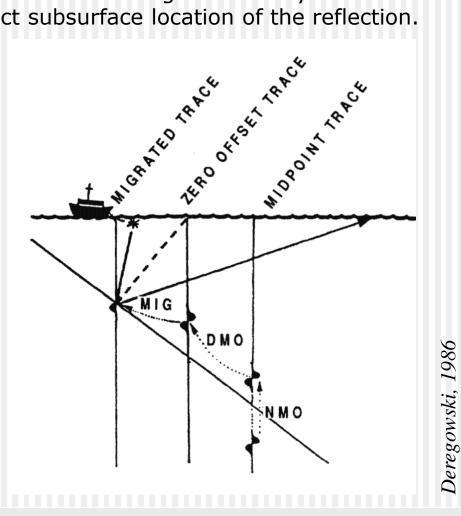
- Groups of CMP gathers are NMO-corrected (hyperbolas flattened) using a range of trial velocities and stacked.
- Velocities are picked at the amplitude peaks and best resolution in the stacks.





NMO→DMO→Migration

- DMO assists NMO by correcting for the time delay on an offset trace assuming zero dip.
- For a dipping reflector and a given source-receiver pair, DMO shifts the time of the NMO-corrected reflection and its position to those of the correct zero-offset trace. Migration finally moves it to the correct subsurface location of the reflection.



CMP Processing Sequence (continued)

17) CMP Stack

- Produces a zero-offset section;
- Utilizes CMP redundancy to increase the Signal/Noise ratio.
- Can employ various normalization ideas, e.g., diversity stack
- 18) Migration
 - Transforms the zero-offset time section into a depth image;
 - Establishes correct extents and dips of the reflectors.
- 19) Frequency filtering and display
 - Attenuates noise
 - Provides best display for interpretation



Moveout (f-k, τ -p) filtering

Removes coherent events with <u>undesired moveouts</u>

NMO applied

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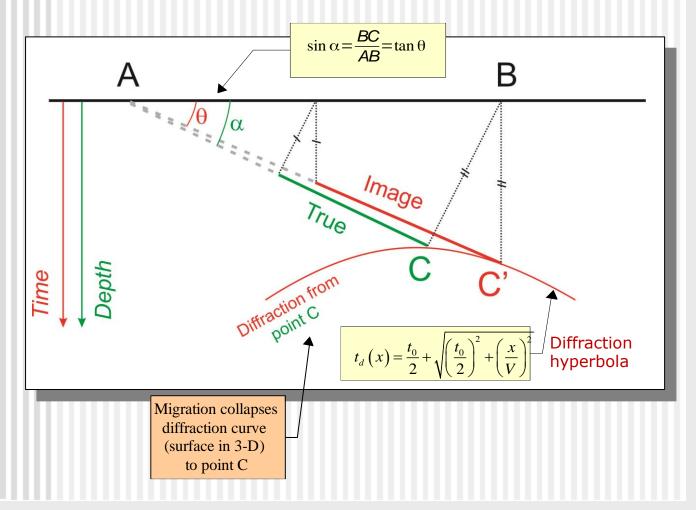
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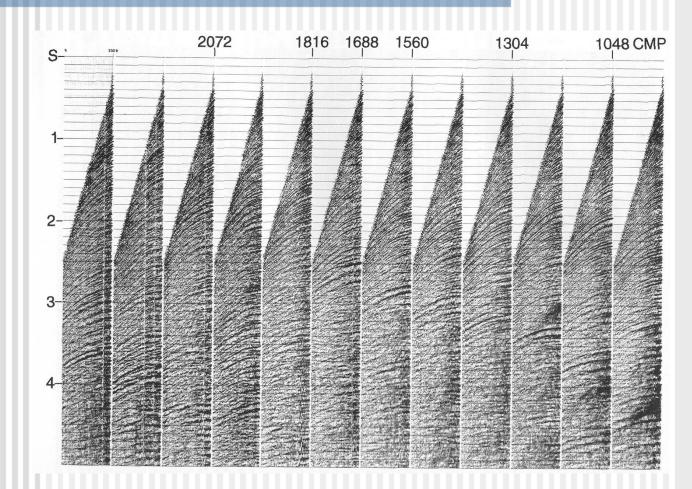
Migration

- A simplified variant of '*inversion*' (without changing amplitudes)
 - Inverts 'time section' for true 'depth image'
- Establishes true positions (AC in plot) and dips (α) of reflectors.
- Collapses diffractions



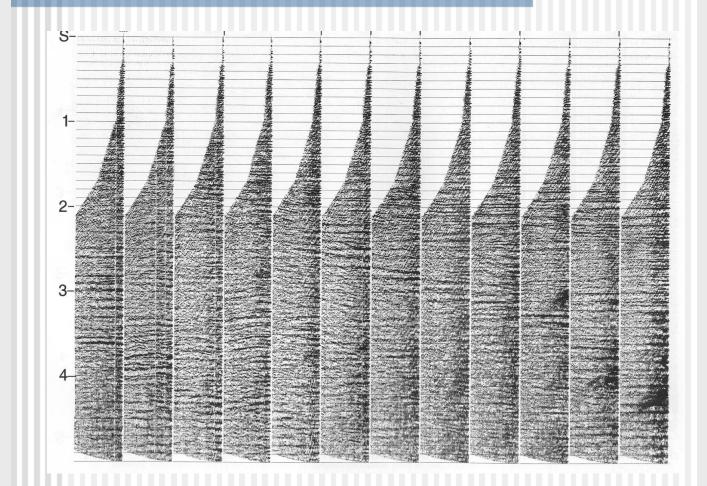


Example: CMP gathers





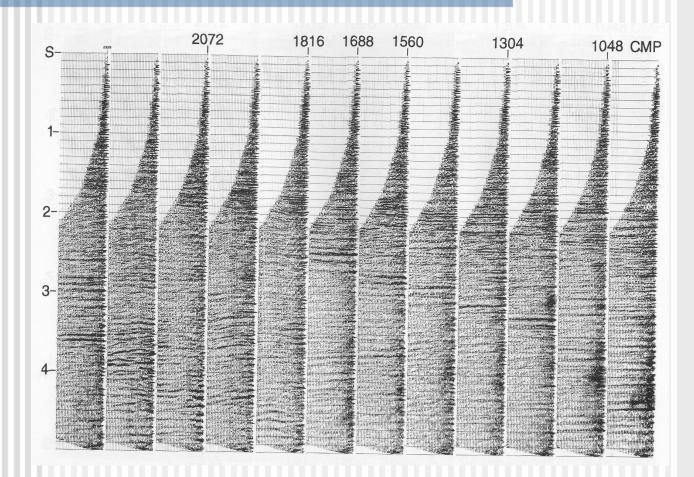
Example: CMP gathers after NMO correction



- Note some imperfectly corrected reflections because of stacking velocities being dependent on conflicting dips
- Also, multiples are "frowning" (under-corrected), because stacking velocities for multiples are typically lower than for primary reflections at the same depth.



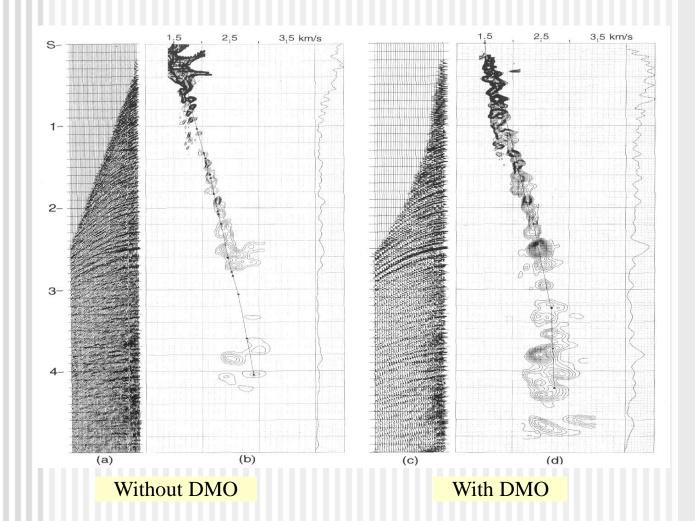
Example: CMP gathers after NMO+DMO corrections



- Note that after DMO, the problem of conflicting dips is resolved
- Some multiples are still "frowning", but this means that they will be removed by stacking



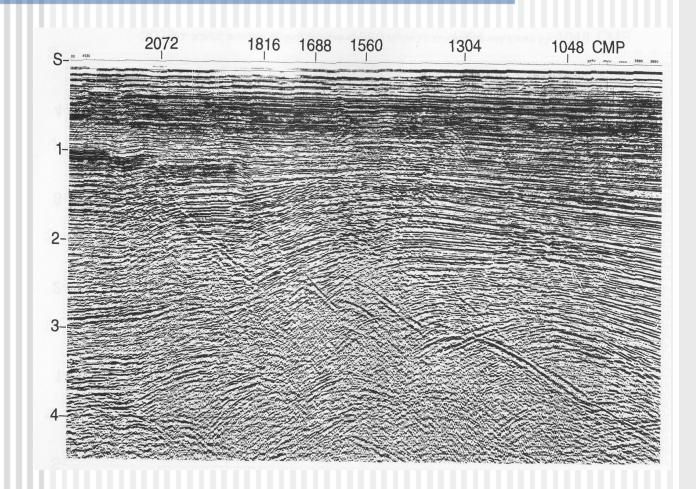
Example: Velocity analysis



 Note the improved accuracy of velocity picking and increased semblance values after DMO



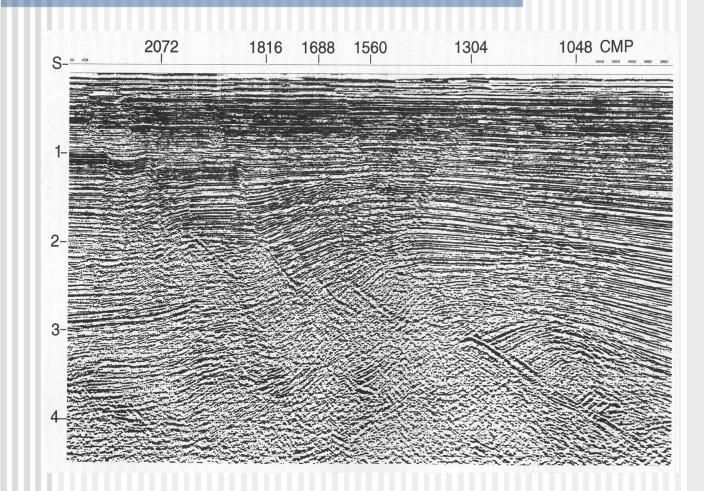
Example: NMO (with DMO) stack Zero-offset section



 Note the criss-crossing reflections and incorrect positions of dipping structures in the time section before migration



Example: Final migrated stack



Note that structures, positions, and dips are finally correct